

CE SAR TEST REPORT

For

ASBISc Enterprises PLC

Kids Smartwatch

Model No.: CNE-KW21, CNE-KW21XX(XX could be A-Z)

Prepared For : ASBISc Enterprises PLC
Address : 43 Kolonakiou street, Diamond Court, 4103, Ayios Athabasios, Limassol,
Cyprus

Prepared By : Shenzhen Anbotek Compliance Laboratory Limited
Address : 1/F, Building D, Sogood Science and Technology Park, Sanwei
community, Hangcheng Street, Bao'an District, Shenzhen, Guangdong,
China.518102
Tel: (86) 755-26066440 Fax: (86) 755-26014772

Report Number : SZAWW1901030011-03H

Date of Receipt : Jan. 03, 2019

Date of Test : Jan. 09~ 15, 2019

Date of Report : Jan. 18, 2019

Contents

1. Statement of Compliance.....	6
2. General Information.....	7
2.1 Client Information.....	7
2.2 Testing Laboratory Information.....	7
2.3 Description of Equipment Under Test (EUT).....	7
2.4 Device Category and SAR Limits.....	9
2.5 Applied Standard.....	9
2.6 Environment of Test Site.....	9
2.7 Test Configuration.....	9
3. Specific Absorption Rate (SAR).....	10
3.1 Introduction.....	10
3.2 SAR Definition.....	10
4. SAR Measurement System.....	11
4.1 E-Field Probe.....	12
4.2 Data Acquisition Electronics (DAE).....	12
4.3 Robot.....	13
4.4 Measurement Server.....	13
4.5 Phantom.....	14
4.6 Device Holder.....	15
4.7 Data Storage and Evaluation.....	16
5. Test Equipment List.....	18
6. Tissue Simulating Liquids.....	19
7. System Verification Procedures.....	20
8. EUT Testing Position.....	22
8.1 Face Up Position.....	22
8.2 Limb Worn Position.....	22
9. Measurement Procedures.....	23
9.1 Spatial Peak SAR Evaluation.....	23
9.2 Power Reference Measurement.....	24
9.3 Area & Zoom Scan Procedures.....	24
9.4 Volume Scan Procedures.....	25
9.5 SAR Averaged Methods.....	25
9.6 Power Drift Monitoring.....	25
10. E.I.R.P Power.....	26
11. SAR Test Results Summary.....	27
11.1 Body SAR Results.....	27
12. Measurement Uncertainty.....	28
Appendix A. EUT Photos and Test Setup Photos.....	30
Appendix B. Plots of SAR System Check.....	31
Appendix C. Plots of SAR Test Data.....	33

Appendix D. DASY System Calibration Certificate..... 36

TEST REPORT

Applicant : ASBISc Enterprises PLC
Manufacturer : ASBISc Enterprises PLC
Product Name : Kids Smartwatch
Model No. : CNE-KW21, CNE-KW21XX(XX could be A-Z)
Trade Mark : Canyon
Rating(s) : Input: DC 5V, 300mA (with DC 3.7V, 400 mAh Battery inside)

Test Standard(s) : EN62209-2:2010; EN50566:2017

The device described above is tested by Shenzhen Anbotech Compliance Laboratory Limited to determine the maximum emission levels emanating from the device and the severe levels of the device can endure and its performance criterion. The measurement results are contained in this test report and Shenzhen Anbotech Compliance Laboratory Limited is assumed full of responsibility for the accuracy and completeness of these measurements. Also, this report shows that the EUT (Equipment Under Test) is technically compliant with the EN62209-2:2010 and EN50566:2017 requirements.

This report applies to above tested sample only and shall not be reproduced in part without written approval of Shenzhen Anbotech Compliance Laboratory Limited.

Date of Test

Jan. 09~ 15, 2019

Prepared By



Bobby Wang

(Engineer / Bobby Wang)

Reviewer

Snowy Meng

(Supervisor / Snowy Meng)

Approved & Authorized Signer

Sally Zhang

(Manager / Sally Zhang)

Version

Version No.	Date	Description
01		Original

1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing are as follows.

<Highest SAR Summary>

Frequency Band	Highest 10g-SAR(W/Kg)	
	Face Up (0.5cm Gap)	Limb Worn (0cm Gap)
GSM 900	0.353	0.698
GSM1800	0.298	0.516
SAR Test Limit (W/Kg)	2.0	4.0
Test Result	PASS	

2. General Information

2.1 Client Information

Applicant:	ASBISc Enterprises PLC
Address of Applicant:	43 Kolonakiou street, Diamond Court, 4103, Ayios Athanasios, Limassol, Cyprus
Manufacture:	ASBISc Enterprises PLC
Address of Manufacture:	43 Kolonakiou street, Diamond Court, 4103, Ayios Athanasios, Limassol, Cyprus
Factory:	Jiangsu JinYiDa Energy Technology Co.,Ltd
Address of Factory:	JingKou Industrial Park, JingKou District, Zhenjiang City

2.2 Testing Laboratory Information

Test Site:	Shenzhen Anbotech Compliance Laboratory Limited
Address:	1/F, Building D, Sogood Science and Technology Park, Sanwei community, Hangcheng Street, Bao'an District, Shenzhen, Guangdong, China.518102

2.3 Description of EquipmentUnder Test (EUT)

Equipment	Kids Smartwatch
Brand Name	Canyon
Model No.	CNE-KW21, CNE-KW21XX(XX could be A-Z) (Note: All samples are the same except the appearance, so we prepare "CNE-KW21" for test only.)
Test Sample No.	S1
Test Power Supply	DC 3.7V Battery inside
Tx Frequency	GSM 900: 880 -915 MHz (TX); 935 - 960 MHz (RX) DCS1800: 1710 -1785 MHz (TX); 1805-1880 MHz (RX)
Type of Modulation	GSM900/1800: GMSK
Antenna Type:	GSM900/1800: PIFA Antenna
Antenna Gain(Peak):	GSM 900: -2.53 dBi DCS1800: 0.72 dBi
Category of device	Portable device

Remark:

1. The above DUT's information was declared by manufacturer. Please refer to the specifications or user's manual for more detailed description.

2.4 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user. Limit for General Population/Uncontrolled exposure should be applied for this device, it is 2.0 W/kg as averaged over any 10 gram of tissue.

2.5 Applied Standard

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

- EN 62209-2:2010
- EN50566:2017

2.6 Environment of Test Site

Items	Required	Actual
Temperature (°C)	18-25	22~23
Humidity (%RH)	30-70	55~65

2.7 Test Configuration

The device was controlled by a base station emulator. Communication between the device and the emulator was established by air link. The distance between the EUT and the antenna of the emulator is larger than 50 cm and the output power radiated from the emulator antenna is at least 30 dB smaller than the output power of EUT. The EUT was set from the emulator to radiate maximum output power during all tests.

3. Specific Absorption Rate (SAR)

3.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

3.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$\text{SAR} = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$\text{SAR} = C \left(\frac{\delta T}{\delta t} \right)$$

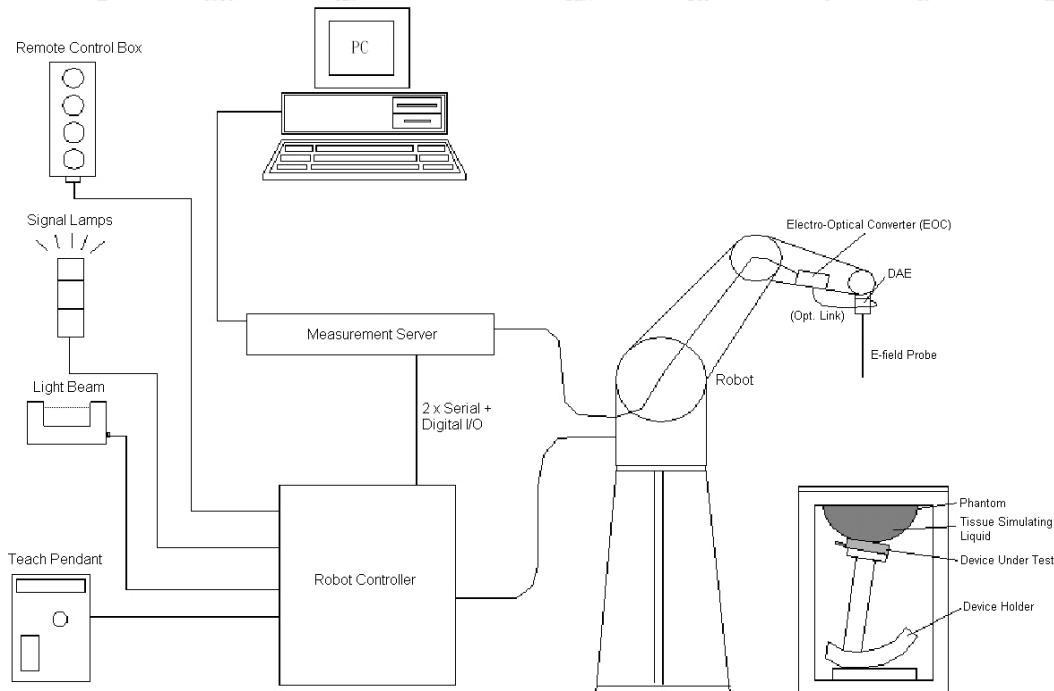
Where: C is the specific heat capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$\text{SAR} = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

4. SAR Measurement System



DASY System Configurations

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (EOC) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY software
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system


components are described in details in the following sub-sections.

4.1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

➤ E-Field Probe Specification

<EX3DV4 Probe>

Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	 Photo of EX3DV4
Frequency	10 MHz to 6 GHz; Linearity: ± 0.2 dB	
Directivity	± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)	
Dynamic Range	10 μ W/g to 100 mW/g; Linearity: ± 0.2 dB (noise: typically < 1 μ W/g)	
Dimensions	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	

➤ E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than $\pm 10\%$. The spherical isotropy shall be evaluated and within ± 0.25 dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

4.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The input impedance of the DAE is 200M Ω ; the inputs are symmetrical and floating. Common mode rejection is above 80dB.

**Photo of DAE**

4.3 Robot

The SPEAG DASY system uses the high precision robots (DASY5: TX60XL) type from Stäubli SA (France). For the 6-axis controllersystem, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäublirobot series have many features that are important for our application:

- High precision (repeatability ± 0.035 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)

**Photo of DASY5**

4.4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5: 128 MB), RAM (DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface

detection, controls robot movements and handles safety operations.



Photo of Server for DASY5

4.5 Phantom

<SAM Twin Phantom>

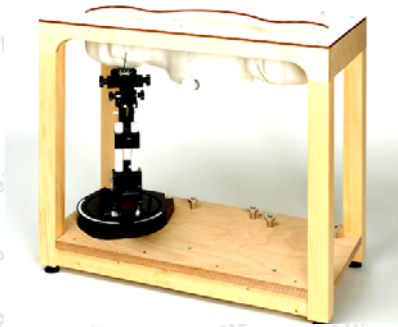
Shell Thickness	2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm	
Filling Volume	Approx. 25 liters	
Dimensions	Length: 1000 mm; Width: 500 mm; Height: adjustable feet	
Measurement Areas	Left Hand, Right Hand, Flat Phantom	

Photo of SAM Phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

<ELI4 Phantom>


Shell Thickness	2 ± 0.2 mm (sagging: <1%)	
Filling Volume	Approx. 30 liters	
Dimensions	Major ellipse axis: 600 mm Minor axis: 400 mm	

Photo of ELI4 Phantom

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

4.6 Device Holder

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of $\pm 0.5\text{mm}$ would produce a SAR uncertainty of $\pm 20\%$. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



Device Holder

4.7 Data Storage and Evaluation

➤ Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

➤ Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Norm _i , a _{i0} , a _{i1} , a _{i2}
	- Conversion factor	ConvF _i
	- Diode compression point	dcp _i
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = compensated signal of channel i , ($i = x, y, z$)

U_i = input signal of channel i , ($i = x, y, z$)

cf = crest factor of exciting field (DASY parameter)

dcp_i = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated:

$$\text{E-field Probes: } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field Probes: } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with V_i = compensated signal of channel i , ($i = x, y, z$)

Norm_i = sensor sensitivity of channel i , ($i = x, y, z$), $\mu\text{V}/(\text{V/m})^2$ for E-field Probes

ConvF = sensitivity enhancement in solution

a_{ij} = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E_i = electric field strength of channel i in V/m

H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

E_{tot} = total field strength in V/m

σ = conductivity in [mho/m] or [Siemens/m]

ρ = equivalent tissue density in g/cm³

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

5. Test Equipment List

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	835MHz System Validation Kit	D835V2	4d154	Jun. 16,2018	Jun. 15,2021
SPEAG	1900MHz System Validation Kit	D1900V2	5d175	Jun. 15,2016	Jun. 14,2019
Rohde & Schwarz	UNIVERSAL RADIO COMMUNICATION TESTER	CMU 200	117888	Nov. 05, 2018	Nov. 04, 2019
SPEAG	Data Acquisition Electronics	DAE4	387	Sept. 06,2018	Sept. 05,2019
SPEAG	Dosimetric E-Field Probe	EX3DV4	7396	May 12,2018	May 11,2019
Agilent	ENA Series Network Analyzer	E5071C	MY46317418	May.23, 2018	May. 22, 2019
SPEAG	DAK	DAK-3.5	1226	NCR	NCR
SPEAG	SAM Twin Phantom	QD000P40CD	1802	NCR	NCR
SPEAG	ELI Phantom	QDOVA004AA	2058	NCR	NCR
AR	Amplifier	ZHL-42W	QA1118004	NCR	NCR
Agilent	Power Meter	N1914A	MY50001102	Nov. 05, 2018	Nov. 04, 2019
Agilent	Power Sensor	N8481H	MY51240001	Nov. 05, 2018	Nov. 04, 2019
R&S	Spectrum Analyzer	N9020A	MY51170037	Nov. 05, 2018	Nov. 04, 2019
Agilent	Signal Generation	N5182A	MY48180656	Nov. 05, 2018	Nov. 04, 2019
Worken	Directional Coupler	0110A05601O-10	COM5BNW1A2	Nov. 05, 2018	Nov. 04, 2019

Note:

1. The calibration certificate of DASY can be referred to appendix C of this report.
2. The dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
3. The Insertion Loss calibration of Dual Directional Coupler and Attenuator were characterized via the network analyzer and compensated during system check.
4. The dielectric probe kit was calibrated via the network analyzer, with the specified procedure (calibrated in pure water) and calibration kit (standard) short circuit, before the dielectric measurement. The specific procedure and calibration kit are provided by Agilent.
5. In system check we need to monitor the level on the power meter, and adjust the power amplifier level to have precise power level to the dipole; the measured SAR will be normalized to 1W input power according to the ratio of 1W to the input power to the dipole. For system check, the calibration of the power amplifier is deemed not critically required for correct measurement; the power meter is critical and we do have calibration for it

6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous head tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown as followed:



Photo of Liquid Height for Head SAR

Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Preventol (%)	DGBE (%)	Conductivity (σ)	Permittivity (ϵ_r)
For Head								
900	40.3	57.9	0.2	1.4	0.2	0	0.97	41.5
1800,1900,2000	55.2	0	0	0.3	0	44.5	1.40	40.0

The following table shows the measuring results for simulating liquid.

Measured Frequency (MHz)	Target Tissue		Measured Tissue				Liquid Temp.	Test Date
	ϵ_r	σ	ϵ_r	Dev. (%)	σ	Dev. (%)		
900	41.5	0.97	41.81	0.75	0.97	0	22.2	01/09/2019
1800	40.0	1.40	41.56	3.90	1.38	-1.43	21.6	01/15/2019

7. System Verification Procedures

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

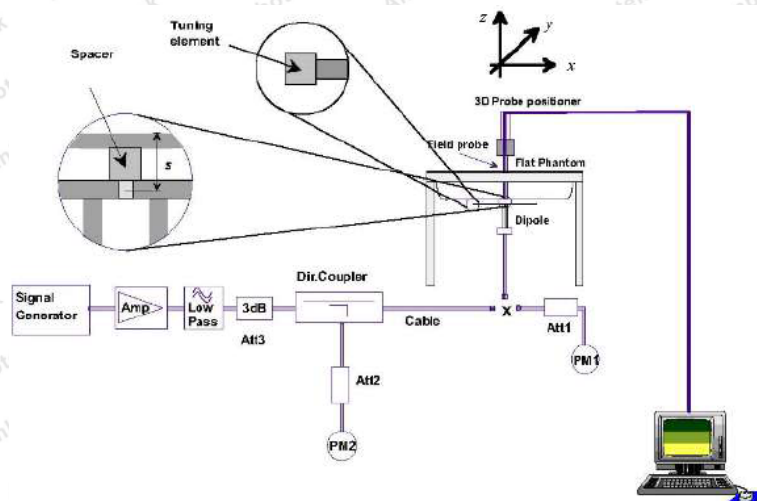
➤ Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

➤ System Setup

A flat phantom shall be used with the tissue-equivalent liquid for system check and system validation. The specifications for the flat phantom are given in Annex A.

For dipole sources the feed-point shall be centred beneath the flat phantom, and the dipole arms shall be aligned with the major or long axis of the phantom. The relative permittivity of the phantom shell material shall be between 2 and 5; however, less than 2 may be acceptable only below 3 GHz. The thickness of the flat phantom bottom section shall be 2 mm. The thickness shall be uniform within a tolerance of ± 0.2 mm. The loss tangent of the phantom shell material shall be less than or equal to 0.05. The material shall be resistant to damage or reaction with tissue-equivalent liquid chemicals. When filled with liquid, sagging at the liquid interface and inner surface of the phantom directly above the source (e.g. a dipole) shall be less than 1 % of the free-space wavelength in the frequency range of 800 MHz to 6 000 MHz, and less than 0,5 % of the free-space wavelength at frequencies below 800 MHz. To minimize reflections from the upper surface of the tissue-equivalent liquid, the depth of the liquid shall be at least 15 cm. Liquid depth of less than 15 cm can be used if it is demonstrated (e.g. using numerical simulations) that the effect on peak spatial-average SAR is less than 1 % of the measured SAR under worst-case conditions. If it is more than 1 % but less than 3 %, the worst-case value shall be added to the uncertainty budget.



System Setup for System Evaluation

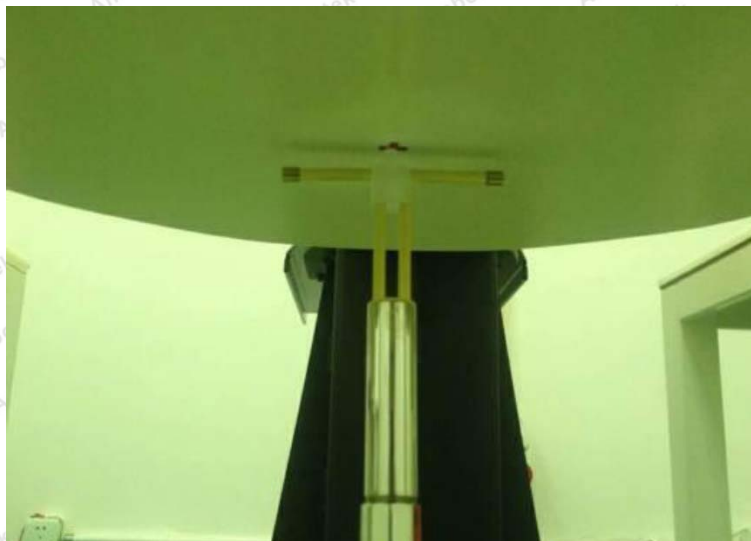


Photo of Dipole Setup

➤ Validation Results

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10 %. The table below shows the target SAR and measured SAR after normalized to 1W input power. It indicates that the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

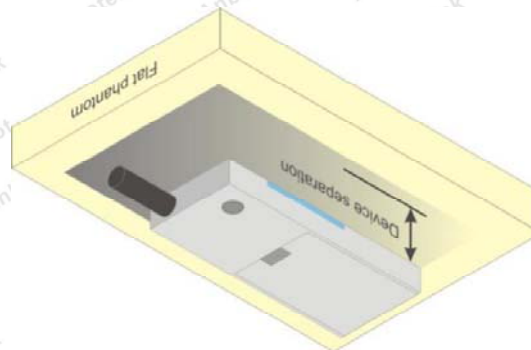
Frequency (MHz)	Power fed onto reference dipole (mW)	Targeted SAR 10g(W/kg)	Measured SAR 10g(W/kg)	Normalized SAR 10g(W/kg)	Deviation (%)	Test Date
900	250	6.91	1.75	7.00	1.30	01/09/2019
1800	250	19.80	4.84	19.36	-2.22	01/15/2019

Target and Measurement SAR after Normalized

8. EUT Testing Position

8.1 Face Up Position

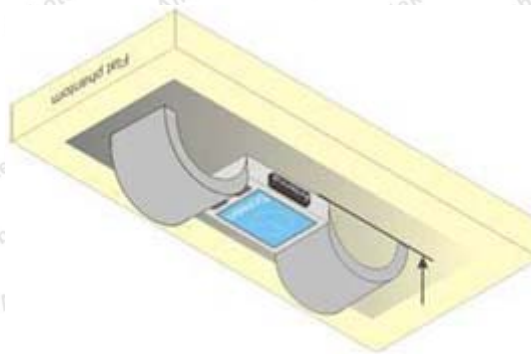
- (a) To position the device parallel to the phantom surface with screen up.
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 0.5 cm.



Face Up Position

8.2 Limb Worn Position

- (a) To open the strap so that it is divided into two parts as shown.
- (b) To adjust the device parallel to the flat phantom.
- (c) To adjust the distance between the device surface and the flat phantom to 0 cm



Limb worn Position

9. Measurement Procedures

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the middle channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as setup photos demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR transmitting at the middle channel for all applicable exposure positions.
- (g) Identify the exposure position and device configuration resulting the highest SAR
- (h) Measure SAR at the lowest and highest channels at the worst exposure position and device configuration if applicable.

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

9.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

9.2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

9.3 Area & Zoom Scan Procedures

Measure the local SAR at a test point within 8 mm of the phantom inner surface that is closest to the DUT.

Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grid spacing of 20 mm for frequencies below 3 GHz and $(60/f \text{ [GHz]})$ mm for frequencies of 3 GHz and greater is recommended. The maximum distance between the geometrical center of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\ln(2)/2$ mm for frequencies of 3 GHz and greater, where $\ln(x)$ is the natural logarithm. The maximum variation of the sensor-phantom surface distance shall be 1 mm for frequencies below 3 GHz and 0.5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5° . If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional uncertainty evaluation is needed.

From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that will not be within the zoom scan of other peaks; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR compliance limit (e.g., 1 W/kg for 1.6 W/kg 1 g limit, or 1.26 W/kg for 2 W/kg, 10 g limit).

Measure the three-dimensional SAR distribution at the local maxima locations identified in step c) (zoom scan procedure). The horizontal grid step shall be $(24 / f \text{ [GHz]})$ mm or less but not more than 8 mm. The minimum zoom scan size is 30 mm by 30 mm by 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom scan size can be reduced to 22 mm by 22 mm by 22 mm. The grid step in the vertical direction shall be $(8 \cdot f \text{ [GHz]})$ mm or less but not more than 5 mm, if uniform spacing is used (Annex C.3.3 of IEC 62209-1:2005). If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be $(12/f \text{ [GHz]})$ mm or less but not more than 4 mm, and the spacing between farther points shall increase by an incremental factor not exceeding 1.5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical center of the probe detectors and the

inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\ln(2)/2$ mm for frequencies of 3 GHz and greater, where the plane wave skin depth and $\ln(x)$ is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved if the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the flat phantom surface shall be less than 5°.

9.4 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

9.5 SAR Averaged Methods

In DASY, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

9.6 Power Drift Monitoring

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

10.E.I.R.P Power

<GSM E.I.R.P. power>

Band GSM900	Burst Average Power (dBm)			Frame-Average Power (dBm)		
TX Channel	975	37	124	975	37	124
Frequency (MHz)	880.2	897.6	914.8	880.2	897.6	914.8
GSM (GMSK, 1 Tx slot)	32.56	33.13	33.18	23.53	24.15	24.15
GPRS (GMSK, 1 Tx slot) – CS1	28.52	29.03	29.13	19.49	20.10	20.10
GPRS (GMSK, 2 Tx slots) – CS1	28.13	28.36	28.12	22.11	22.34	22.10
GPRS (GMSK, 3 Tx slots) – CS1	28.23	28.61	28.50	23.97	24.35	24.24
GPRS (GMSK, 4 Tx slots) – CS1	28.07	28.03	28.13	25.06	25.02	25.12
Band GSM1800	Burst Average Power (dBm)			Frame-Average Power (dBm)		
TX Channel	512	698	885	512	698	885
Frequency (MHz)	1710.2	1747.6	1784.8	1710.2	1747.6	1784.8
GSM (GMSK, 1 Tx slot)	30.14	30.15	30.46	21.11	21.43	21.43
GPRS (GMSK, 1 Tx slot) – CS1	27.57	28.80	29.65	18.54	20.62	20.62
GPRS (GMSK, 2 Tx slots) – CS1	27.15	27.27	28.14	21.13	21.25	22.12
GPRS (GMSK, 3 Tx slots) – CS1	26.61	26.55	27.16	22.35	22.29	22.90
GPRS (GMSK, 4 Tx slots) – CS1	26.00	25.60	26.66	22.99	22.59	23.65

Frame-averaged power = Maximum burst averaged power (1 Tx Slot) – 9.03 dB
Frame-averaged power = Maximum burst averaged power (2 Tx Slots) – 6.02 dB
Frame-averaged power = Maximum burst averaged power (3 Tx Slots) - 4.26 dB
Frame-averaged power = Maximum burst averaged power (4 Tx Slots) – 3.01 dB

Note:

1. For Body SAR testing, the mode of highest source-based time-average power among GSM and GPRS is selected to be tested; therefore GSM900 and GSM1800 band GPRS 4 Tx slots is selected.
2. Start tests at middle channel and determine the worst configuration for further high/low channel tests.

11. SAR Test Results Summary

11.1 Body SAR Results

<GSM>

Band	Mode	Test Position	Gap (cm)	Channel	SAR _{10g} (W/kg)	Plot
GSM900	GPRS(4 Tx slots)	Face up	0.5	37	0.353	-
GSM900	GPRS(4 Tx slots)	Limb Worn	0	975	0.647	-
GSM900	GPRS(4 Tx slots)	Limb Worn	0	37	0.698	#1
GSM900	GPRS(4 Tx slots)	Limb Worn	0	124	0.663	-
GSM1800	GPRS(4 Tx slots)	Face up	0.5	698	0.298	-
GSM1800	GPRS(4 Tx slots)	Limb Worn	0	512	0.491	-
GSM1800	GPRS(4 Tx slots)	Limb Worn	0	698	0.516	#2
GSM1800	GPRS(4 Tx slots)	Limb Worn	0	885	0.503	-

12. Measurement Uncertainty

NO	Source	Uncert. ai (%)	Prob. Dist.	Div. k	ci (1g)	ci (10g)	Stand.Un cert. ui (1g)	Stand.Un cert. ui (10g)	V _{eff}
1	Repeat	0.4	N	1	1	1	0.4	0.4	9
Instrument									
2	Probe calibration	7	N	2	1	1	3.5	3.5	∞
3	Axial isotropy	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
4	Hemispherical isotropy	9.4	R	$\sqrt{3}$	0.7	0.7	3.9	3.9	∞
5	Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Linearity	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
7	Detection limits	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
8	Readout electronics	0.3	N	1	1	1	0.3	0.3	∞
9	Response time	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
10	Integration time	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
11	Ambient noise	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
12	Ambient reflections	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Probe positioner mech. restrictions	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞
14	Probe positioning with respect to phantom shell	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
15	Max.SAR evaluation	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Test sample related									

16	Device positioning	3.8	N	1	1	1	3.8	3.8	99
17	Device holder	5.1	N	1	1	1	5.1	5.1	5
18	Drift of output power	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
Phantom and set-up									
19	Phantom uncertainty	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
20	Liquid conductivity (target)	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
21	Liquid conductivity (meas)	2.5	N	1	0.64	0.43	1.6	1.2	∞
22	Liquid Permittivity (target)	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.5	∞
23	Liquid Permittivity (meas)	2.5	N	1	0.6	0.49	1.5	1.2	∞
Combined standard			RSS	$U_c = \sqrt{\sum_{i=1}^n c_i^2 U_i^2}$			11.4%	11.3%	236
Expanded uncertainty(P=95%)		$U = k U_c$ k=2					22.8%	22.6%	

Appendix A. EUT Photos and Test Setup Photos

Face Up (5mm gap)

Limb Worn (0mm gap)

Appendix B. Plots of SAR System Check

900MHz Head System Check

DUT: Dipole 900 MHz; Type: D900V2; Serial: D900V2 - SN:158

Communication System: UID 0, CW; Frequency: 900 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 900 \text{ MHz}$; $\sigma = 0.96 \text{ S/m}$; $\epsilon_r = 42.33$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7396; ConvF(9.87, 9.87, 9.87); Calibrated: 12.05.2018;
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP: 1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

Configuration/Pin=250mW/Area Scan (7x7x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Maximum value of SAR (measured) = 2.72 W/kg

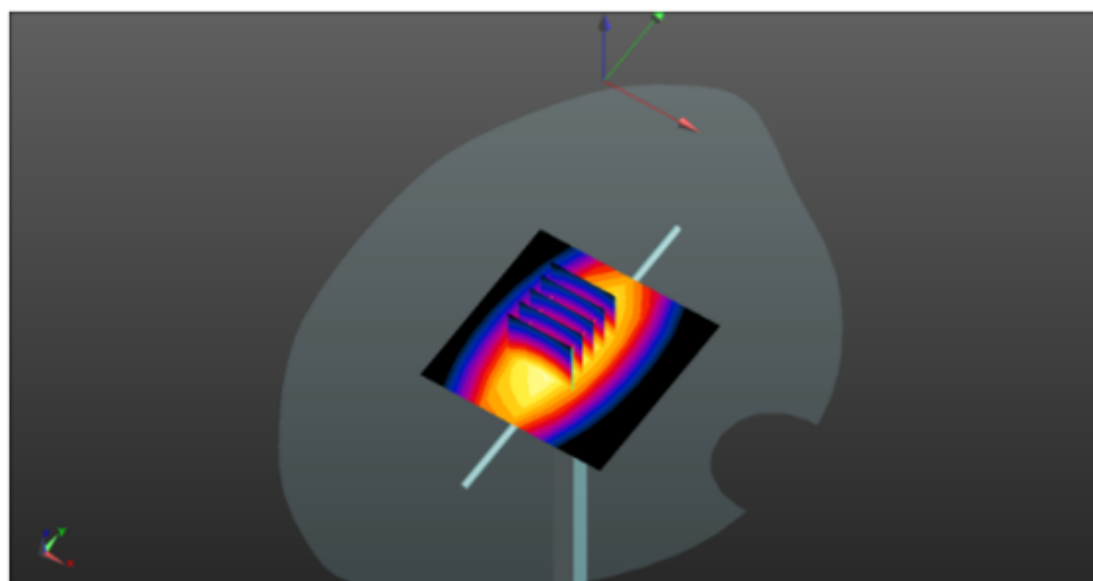
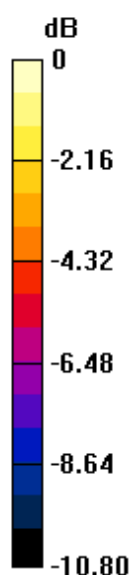
Configuration/Pin=250mW/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$

Reference Value = 60.007 V/m ; Power Drift = 0.02 dB

Peak SAR (extrapolated) = 4.02 W/kg

SAR(1 g) = 2.67 W/kg ; SAR(10 g) = 1.75 W/kg

Maximum value of SAR (measured) = 3.58 W/kg



0 dB = 3.58 W/kg = 5.54 dBW/kg

1800MHz Head System Check**DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN:5d179**

Communication System: UID 0, CW (0); Frequency: 1800 MHz

Medium parameters used: $f = 1800$ MHz; $\sigma = 1.35$ S/m; $\epsilon_r = 40.48$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 – SN7396; ConvF(8.04, 8.04, 8.04); Calibrated: 12.05.2018;
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM ; Type: QD000P40CD; Serial: TP: 1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

Configuration/Pin=250mW/Area Scan (71x71x1): Interpolated grid: dx=1.500 mm, dy=1.500 mm

Maximum value of SAR (interpolated) = 10.7 W/kg

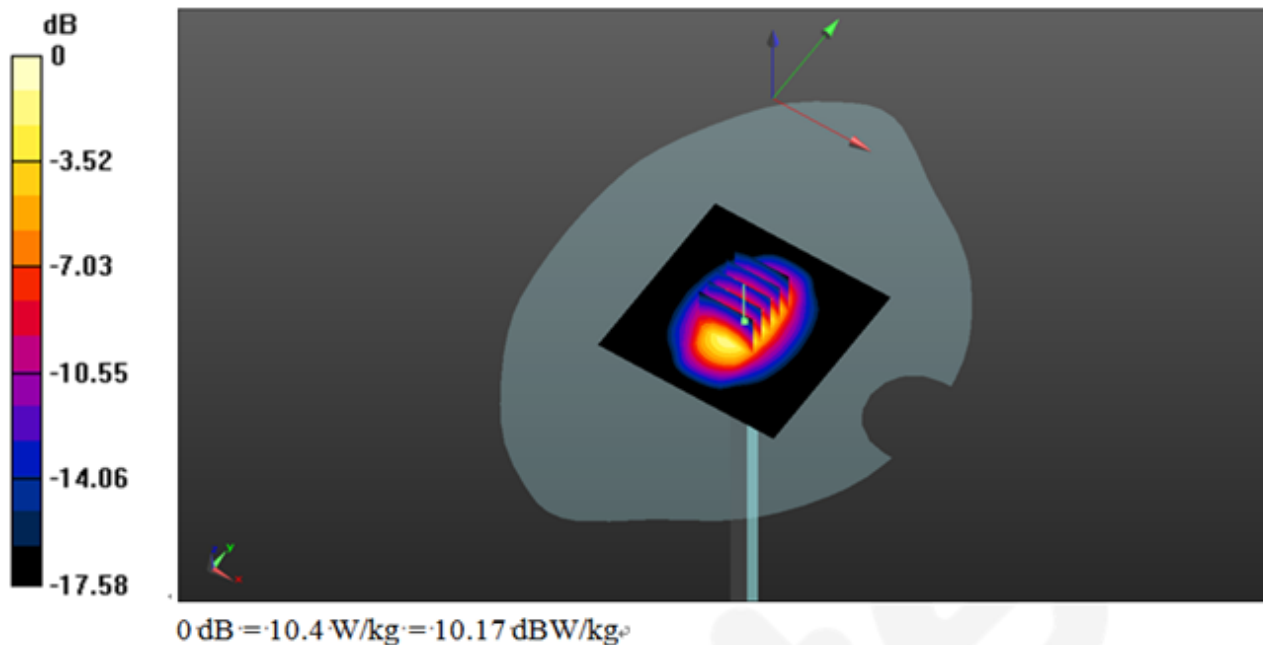
Configuration/Pin=250mW/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 86.92 V/m; Power Drift = 0.02 dB

Peak SAR (extrapolated) = 17.0 W/kg

SAR(1 g) = 9.26 W/kg; SAR(10 g) = 4.84 W/kg

Maximum value of SAR (measured) = 10.4 W/kg



Appendix C. Plots of SAR Test Data

#1

Date: 01/09/2019

EGSM900_GPRS(4 Tx slots)_Back_0cm_Ch37

Communication System: UID 0, GPRS900 (0); Frequency: 897.4 MHz

Medium parameters used (interpolated): $f = 897.4$ MHz; $\sigma = 0.97$ S/m; $\epsilon_r = 42.35$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7396; ConvF(9.87, 9.87, 9.87); Calibrated: 12.05.2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP: 1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

BACK/4ST-H/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 1.19 W/kg

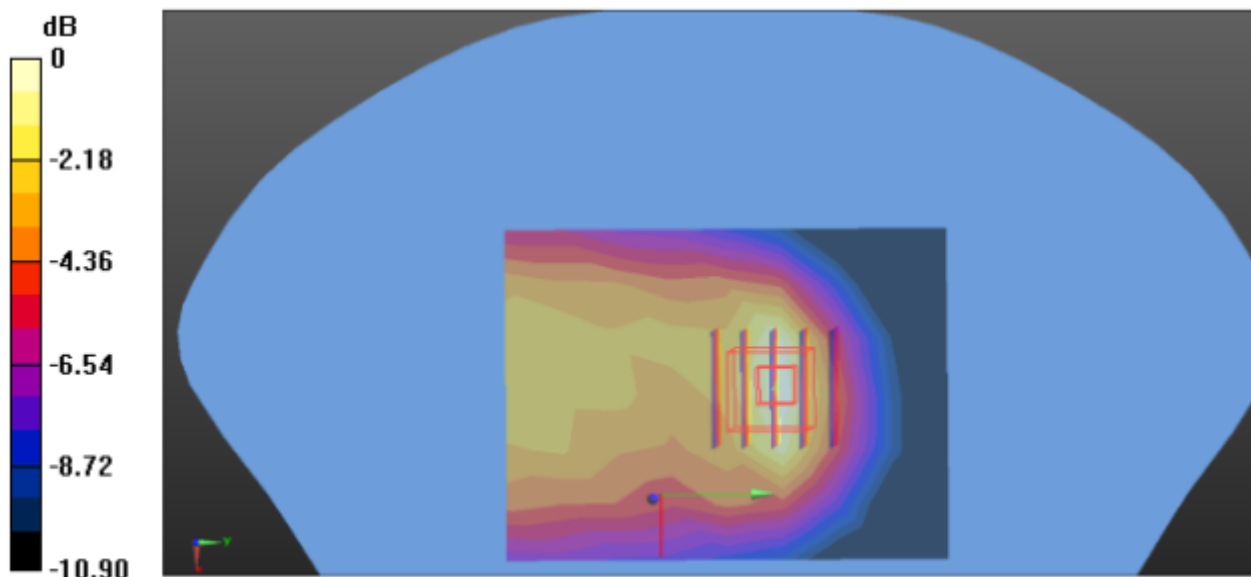
BODY/4ST/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 28.755 V/m; Power Drift = -0.01 dB

Peak SAR (extrapolated) = 1.33 W/kg

SAR(1 g) = 0.999 W/kg; SAR(10 g) = 0.698 W/kg

Maximum value of SAR (measured) = 1.22 W/kg

**0 dB = 1.22 W/kg = 0.86 dBW/kg**

#2

Date: 01/15/2019

DCS1800_GPRS(4 Tx slots)_Back_0cm_Ch698

Communication System: UID 0, GPRS(4 Tx slots) (0); Frequency: 1747.4 MHz

Medium parameters used: $f = 1747.4$ MHz; $\sigma = 1.32$ S/m; $\epsilon_r = 40.34$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7396; ConvF(8.61, 8.61, 8.61); Calibrated: 12.05.2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

Body/4ST-Back-H/Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 1.30 W/kg

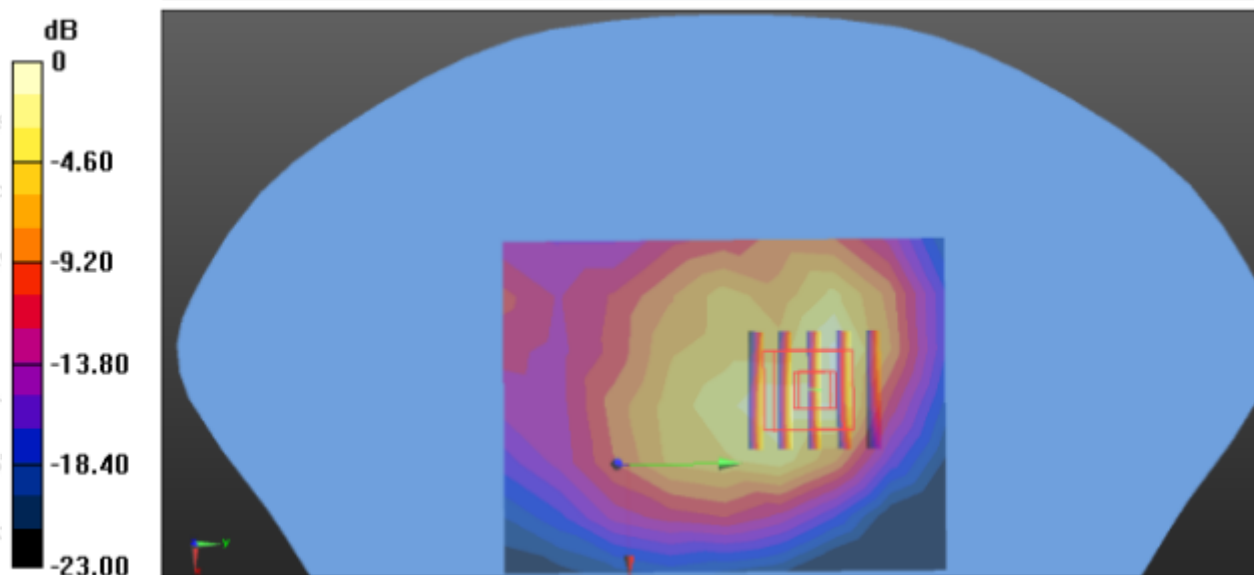
BODY/4ST/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 8.036 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 1.92 W/kg

SAR(1 g) = 0.956 W/kg; SAR(10 g) = 0.516 W/kg

Maximum value of SAR (measured) = 1.39



Appendix D. DASY System Calibration Certificate



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E-mail: cttl@chinattl.com Http://www.chinattl.cn

Client

Anbotech (Auden)

Certificate No: **Z18-98671**

CALIBRATION CERTIFICATE

Object EX3DV4 - SN:7396

Calibration Procedure(s) FF-Z12-006-08
Calibration Procedures for Dosimetric E-field Probes

Calibration date: May 12, 2018

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	20-Jun-17 (CTTL, No.J17X07447)	Jun-18
Power sensor NRP-Z91	101547	20-Jun-17 (CTTL, No.J17X07447)	Jun-18
Power sensor NRP-Z91	101548	20-Jun-17 (CTTL, No.J17X07447)	Jun-18
Reference10dBAttenuator	18N50W-10dB	13-Mar-18(CTTL, No.J18X01547)	Mar-19
Reference20dBAttenuator	18N50W-20dB	13-Mar-18(CTTL, No.J18X01548)	Mar-19
Reference Probe EX3DV4	SN 7433	26-Sep-17(SPEAG, No.EX3-7433_Sep17)	Sep-18
DAE4	SN 549	13-Dec-17(SPEAG, No.DAE4-549_Dec17)	Dec -18
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
SignalGeneratorMG3700A	6201052605	27-Jun-17 (CTTL, No.J17X04776)	Jun-18
Network Analyzer E5071C	MY46110673	13-Jan-18 (CTTL, No.J18X00285)	Jan -19

	Name	Function
Calibrated by:	Yu Zongying	SAR Test Engineer
Reviewed by:	Lin Hao	SAR Test Engineer
Approved by:	Qi Dianyuan	SAR Project Leader

Signature

Issued: May 13, 2018

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: Z18-98671

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E-mail: cttl@chinattl.com Http://www.chinattl.cn

Glossary:

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i $\theta=0$ is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\theta=0$ ($f \leq 900\text{MHz}$ in TEM-cell; $f > 1800\text{MHz}$: waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not effect the E^2 -field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z}** = NORM_{x,y,z} * frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCPx,y,z**: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}**: A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800\text{MHz}$) and inside waveguide using analytical field distributions based on power measurements for $f > 800\text{MHz}$. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from $\pm 50\text{MHz}$ to $\pm 100\text{MHz}$.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).



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Probe EX3DV4

SN: 7396

Calibrated: May 12, 2018

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)



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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm($\mu V/(V/m)^2$) ^A	0.54	0.53	0.50	±10.0%
DCP(mV) ^B	97.8	104.5	102.5	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu V}$	C	D dB	VR mV	Unc ^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	199.9	±2.4%
		Y	0.0	0.0	1.0		203.3	
		Z	0.0	0.0	1.0		195.0	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X, Y, Z do not affect the E²-field uncertainty inside TSL (see Page 5 and Page 6).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.



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Tel: +86-10-62304633-2218 Fax: +86-10-62304633-2209
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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	41.9	0.89	9.82	9.82	9.82	0.30	0.85	± 12.1%
835	41.5	0.90	9.71	9.71	9.71	0.15	1.36	± 12.1%
900	41.5	0.97	9.87	9.87	9.87	0.16	1.37	± 12.1%
1750	40.1	1.37	8.61	8.61	8.61	0.25	1.04	± 12.1%
1900	40.0	1.40	8.13	8.13	8.13	0.24	1.01	± 12.1%
2100	39.8	1.49	8.14	8.14	8.14	0.24	1.04	± 12.1%
2300	39.5	1.67	7.85	7.85	7.85	0.40	0.75	± 12.1%
2450	39.2	1.80	7.57	7.57	7.57	0.50	0.75	± 12.1%
2600	39.0	1.96	7.38	7.38	7.38	0.64	0.68	± 12.1%
5250	35.9	4.71	5.33	5.33	5.33	0.45	1.30	± 13.3%
5600	35.5	5.07	4.89	4.89	4.89	0.45	1.35	± 13.3%
5750	35.4	5.22	4.92	4.92	4.92	0.45	1.45	± 13.3%

^C Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	55.5	0.96	10.09	10.09	10.09	0.30	0.90	±12.1%
835	55.2	0.97	9.88	9.88	9.88	0.19	1.32	±12.1%
900	55.0	1.05	9.82	9.82	9.82	0.23	1.15	±12.1%
1750	53.4	1.49	8.24	8.24	8.24	0.24	1.06	±12.1%
1900	53.3	1.52	7.97	7.97	7.97	0.19	1.24	±12.1%
2100	53.2	1.62	8.18	8.18	8.18	0.19	1.39	±12.1%
2300	52.9	1.81	7.88	7.88	7.88	0.55	0.80	±12.1%
2450	52.7	1.95	7.53	7.53	7.53	0.46	0.89	±12.1%
2600	52.5	2.16	7.38	7.38	7.38	0.52	0.80	±12.1%
5250	48.9	5.36	4.93	4.93	4.93	0.45	1.80	±13.3%
5600	48.5	5.77	4.19	4.19	4.19	0.48	1.90	±13.3%
5750	48.3	5.94	4.52	4.52	4.52	0.48	1.95	±13.3%

^C Frequency validity above 300 MHz of ± 100 MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is $\pm 10, 25, 40, 50$ and 70 MHz for ConvF assessments at $30, 64, 128, 150$ and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to $\pm 10\%$ if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to $\pm 5\%$. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

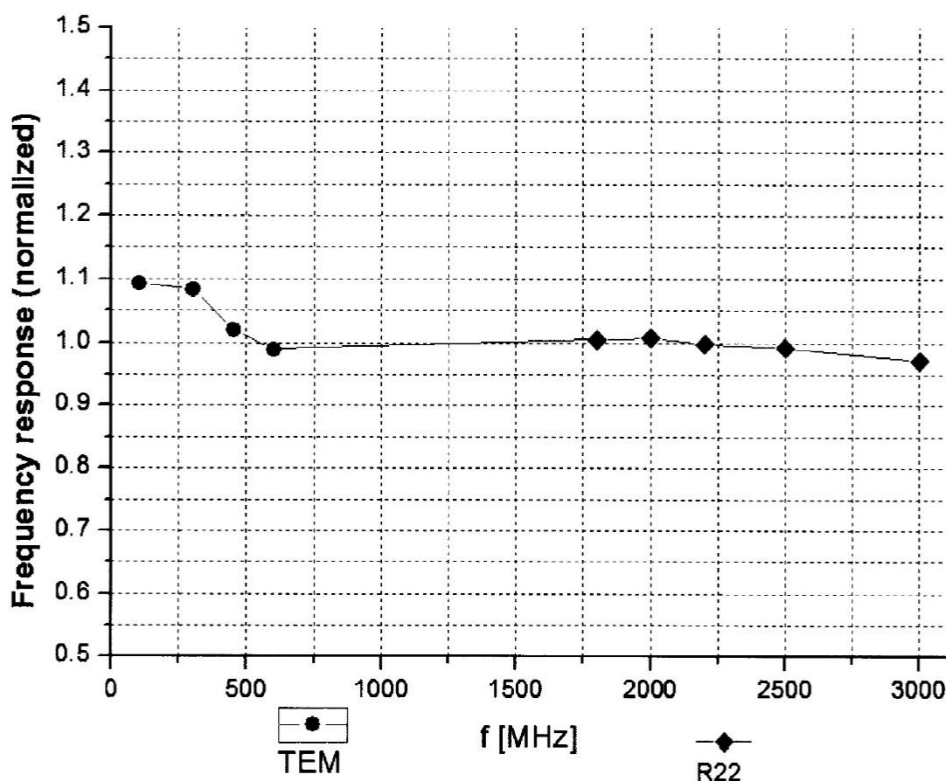
^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than $\pm 1\%$ for frequencies below 3 GHz and below $\pm 2\%$ for the frequencies between $3-6$ GHz at any distance larger than half the probe tip diameter from the boundary.



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Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: $\pm 7.4\%$ ($k=2$)



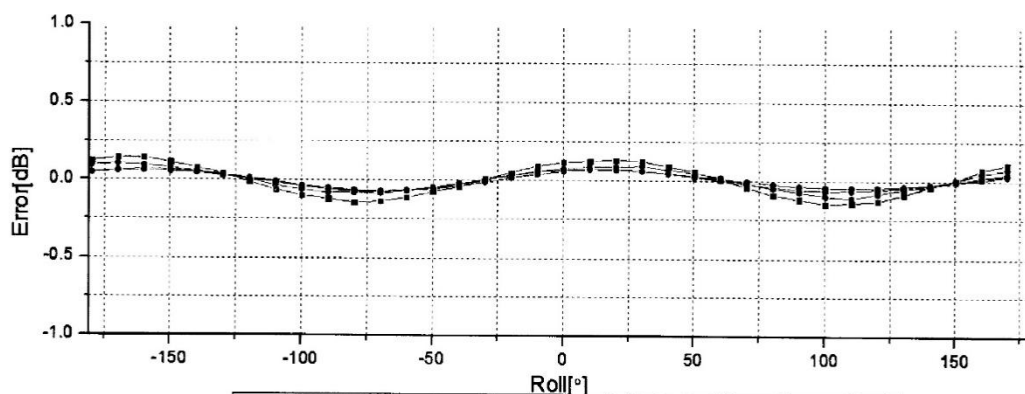
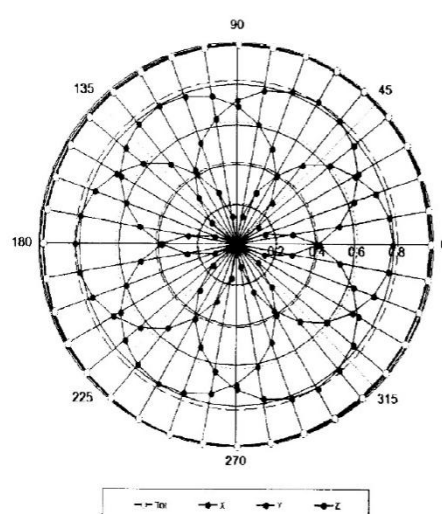
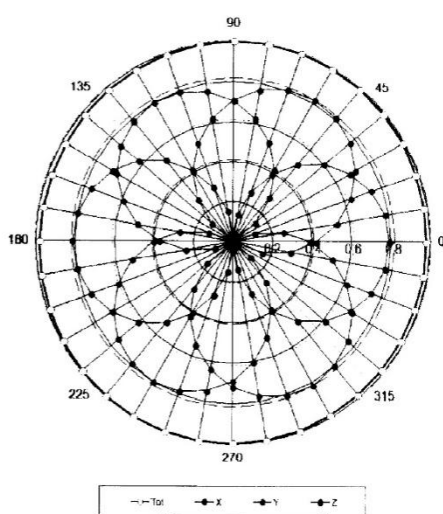
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Receiving Pattern (Φ), $\theta=0^\circ$

f=600 MHz, TEM

f=1800 MHz, R22



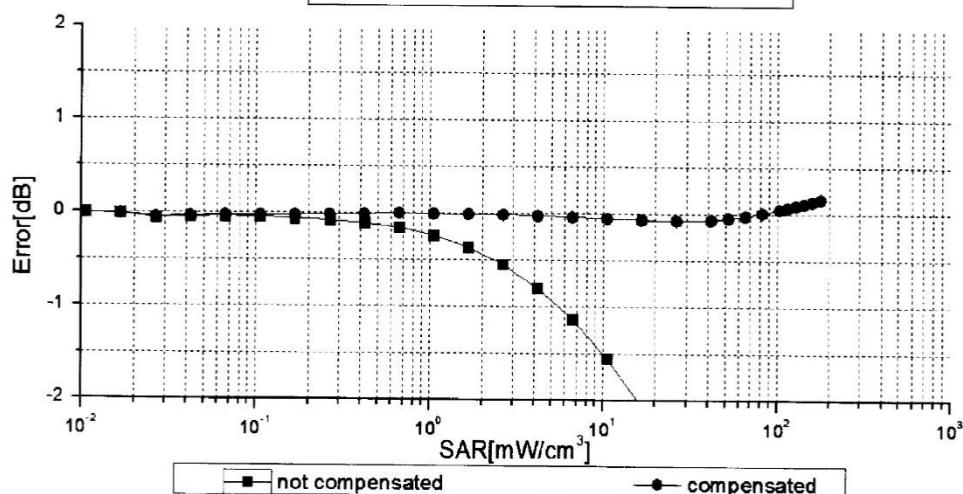
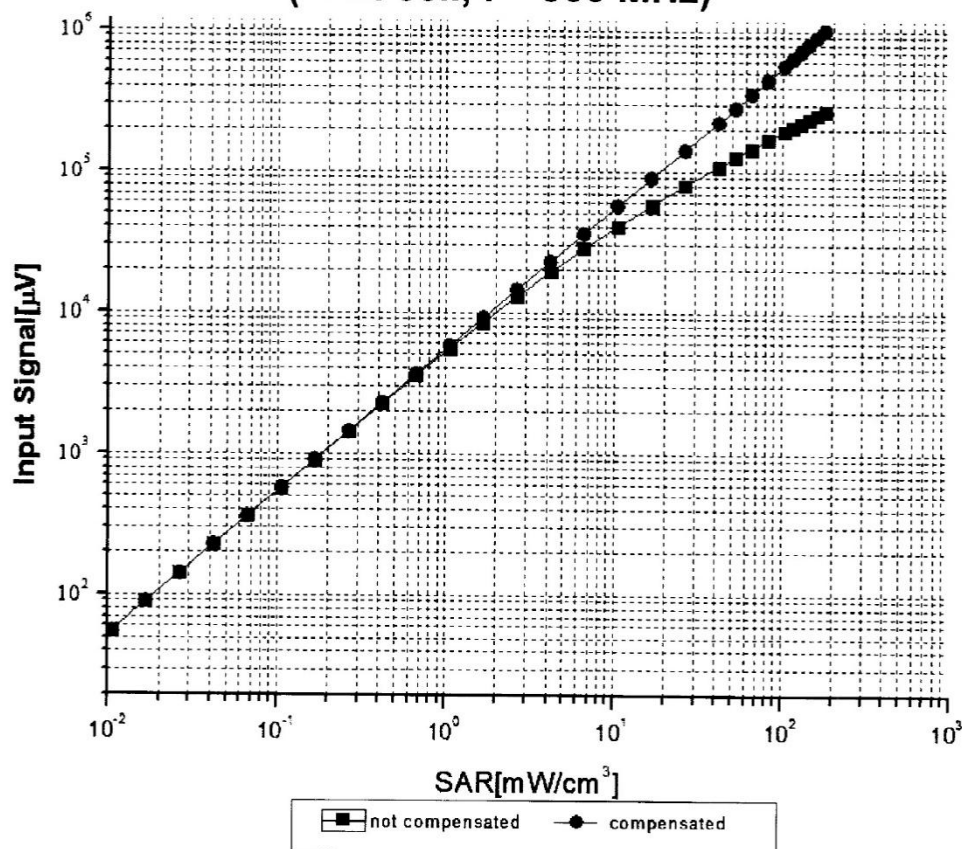
Uncertainty of Axial Isotropy Assessment: $\pm 1.2\%$ ($k=2$)



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Dynamic Range $f(\text{SAR}_{\text{head}})$ (TEM cell, $f = 900 \text{ MHz}$)



Uncertainty of Linearity Assessment: $\pm 0.9\%$ ($k=2$)

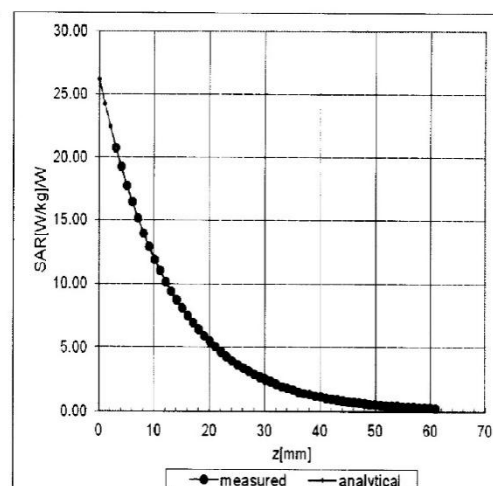
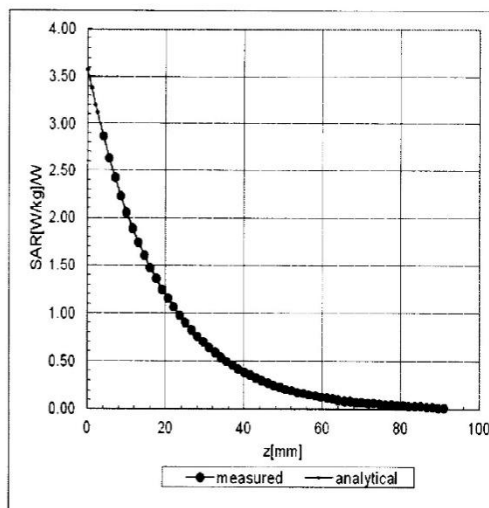


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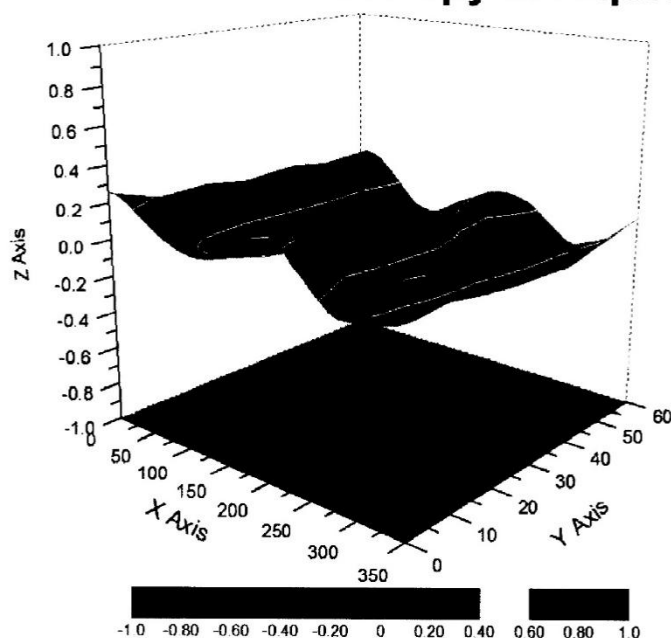
Conversion Factor Assessment

f=900 MHz, WGLS R9(H_convF)

f=1750 MHz, WGLS R22(H_convF)



Deviation from Isotropy in Liquid



Uncertainty of Spherical Isotropy Assessment: $\pm 3.2\%$ (K=2)

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E-mail: cttl@chinattl.com [Http://www.chinattl.cn](http://www.chinattl.cn)**DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396****Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle (°)	156.9
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	9mm
Tip Diameter	2.5mm
Probe Tip to Sensor X Calibration Point	1mm
Probe Tip to Sensor Y Calibration Point	1mm
Probe Tip to Sensor Z Calibration Point	1mm
Recommended Measurement Distance from Surface	1.4mm

Schmid & Partner Engineering AG

s p e a gZeughausstrasse 43, 8004 Zurich, Switzerland
Phone +41 44 245 9700, Fax +41 44 245 9779
info@speag.com, <http://www.speag.com>

IMPORTANT NOTICE

USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.

Schmid & Partner Engineering

TN_BR040315AD DAE4.doc

11.12.2009

**Calibration Laboratory of
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Engineering AG**
Zeughausstrasse 43, 8004 Zurich, Switzerland



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C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **Anbotek (Auden)**

Certificate No: **DAE4-387_Sep08**

CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BM - SN: 387**

Calibration procedure(s) **QA CAL-06.v29
Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **September 06, 2018**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^{\circ}\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	15-Aug-18 (No:21092)	Aug-19
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit Calibrator Box V2.1	SE UWS 053 AA 1001	05-Jan-18 (in house check)	In house check: Jan-19
	SE UMS 006 AA 1002	05-Jan-18 (in house check)	In house check: Jan-19

Calibrated by:	Name Dominique Steffen	Function Laboratory Technician	Signature
Approved by:	Sven Kühn	Deputy Manager	

Issued: September 03, 2018

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Accredited by the Swiss Accreditation Service (SAS)
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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- **DC Voltage Measurement:** Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- **Connector angle:** The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - **DC Voltage Measurement Linearity:** Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - **Common mode sensitivity:** Influence of a positive or negative common mode voltage on the differential measurement.
 - **Channel separation:** Influence of a voltage on the neighbor channels not subject to an input voltage.
 - **AD Converter Values with inputs shorted:** Values on the internal AD converter corresponding to zero input voltage
 - **Input Offset Measurement:** Output voltage and statistical results over a large number of zero voltage measurements.
 - **Input Offset Current:** Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - **Input resistance:** Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - **Low Battery Alarm Voltage:** Typical value for information. Below this voltage, a battery alarm signal is generated.
 - **Power consumption:** Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV, full range = -100...+300 mV

Low Range: 1LSB = 61nV, full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.489 ± 0.02% (k=2)	404.852 ± 0.02% (k=2)	404.862 ± 0.02% (k=2)
Low Range	3.97827 ± 1.50% (k=2)	3.95875 ± 1.50% (k=2)	3.97982 ± 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	53.0 ° ± 1 °
---	--------------

Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

High Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	200032.85	-3.31	-0.00
Channel X + Input	20007.64	1.88	0.01
Channel X - Input	-20003.48	1.18	-0.01
Channel Y + Input	200034.23	-1.43	-0.00
Channel Y + Input	20006.60	0.91	0.00
Channel Y - Input	-20004.04	0.72	-0.00
Channel Z + Input	200035.38	-0.83	-0.00
Channel Z + Input	20003.69	-2.11	-0.01
Channel Z - Input	-20006.38	-1.59	0.01

Low Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	2001.63	0.08	0.00
Channel X + Input	202.29	0.70	0.35
Channel X - Input	-197.90	0.60	-0.30
Channel Y + Input	2001.33	-0.07	-0.00
Channel Y + Input	200.86	-0.60	-0.30
Channel Y - Input	-199.87	-1.23	0.62
Channel Z + Input	2001.61	0.27	0.01
Channel Z + Input	200.60	-0.70	-0.35
Channel Z - Input	-199.51	-0.85	0.43

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	13.50	11.56
	- 200	-8.64	-11.18
Channel Y	200	-0.81	-1.28
	- 200	1.05	0.09
Channel Z	200	7.17	6.91
	- 200	-9.46	-9.01

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	-1.70	0.33
Channel Y	200	10.70	-	-0.38
Channel Z	200	7.11	7.89	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15969	17466
Channel Y	15661	16162
Channel Z	15990	16190

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	0.73	-2.58	3.29	0.62
Channel Y	0.41	-0.49	1.23	0.40
Channel Z	-0.80	-1.88	0.30	0.42

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (k Ω m)	Measuring (M Ω m)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



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E-mail: cttl@chinattl.com [Http://www.chinattl.cn](http://www.chinattl.cn)

Client Anbotek (Auden)

Certificate No: Z18-97089

CALIBRATION CERTIFICATE

Object D835V2 - SN: 4d154

Calibration Procedure(s) FD-Z11-2-003-01
Calibration Procedures for dipole validation kits

Calibration date: Jun 16, 2018

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	01-Jul-17 (CTTL, No.J17X04256)	Jun-18
Power sensor NRP-Z91	101547	01-Jul-17 (CTTL, No.J17X04256)	Jun-18
Reference Probe EX3DV4	SN 7307	19-Feb-18(SPEAG,No.EX3-7307_Feb18)	Feb-19
DAE4	SN 771	02-Feb-18(CTTL-SPEAG,No.Z18-97011)	Feb-19
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Signal Generator E4438C	MY49071430	01-Feb-18 (CTTL, No.J18X00893)	Jan-19
Network Analyzer E5071C	MY46110673	26-Jan-18 (CTTL, No.J18X00894)	Jan-19

	Name	Function	Signature
Calibrated by:	Zhao Jing	SAR Test Engineer	
Reviewed by:	Qi Dianyuan	SAR Project Leader	
Approved by:	Lu Bingsong	Deputy Director of the laboratory	

Issued: Jun 17, 2018

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Certificate No: Z18-97089

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Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM _{x,y,z}
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) For hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- IEC 62209-2, "Procedure to measure the Specific Absorption Rate (SAR) For wireless communication devices used in close proximity to the human body (frequency range of 30MHz to 6GHz)", March 2010
- KDB865664, SAR Measurement Requirements for 100 MHz to 6 GHz

Additional Documentation:

- DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor $k=2$, which for a normal distribution Corresponds to a coverage probability of approximately 95%.



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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	52.8.8.1258
Extrapolation	Advanced Extrapolation	
Phantom	Triple Flat Phantom 5.1C	
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	835 MHz \pm 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	41.5	0.90 mho/m
Measured Head TSL parameters	(22.0 \pm 0.2) °C	41.0 \pm 6 %	0.89 mho/m \pm 6 %
Head TSL temperature change during test	<1.0 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	2.30 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	9.24 mW / g \pm 20.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Head TSL	Condition	
SAR measured	250 mW input power	1.50 mW / g
SAR for nominal Head TSL parameters	normalized to 1W	6.02 mW / g \pm 20.4 % (k=2)

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	55.2	0.97 mho/m
Measured Body TSL parameters	(22.0 \pm 0.2) °C	55.4 \pm 6 %	0.99 mho/m \pm 6 %
Body TSL temperature change during test	<1.0 °C	----	----

SAR result with Body TSL

SAR averaged over 1 cm ³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	2.43 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	9.57 mW / g \pm 20.8 % (k=2)
SAR averaged over 10 cm ³ (10 g) of Body TSL	Condition	
SAR measured	250 mW input power	1.61 mW / g
SAR for nominal Body TSL parameters	normalized to 1W	6.36 mW / g \pm 20.4 % (k=2)

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Page 3 of 8

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E-mail: cttl@chinattl.com Http://www.chinattl.cn**Appendix****Antenna Parameters with Head TSL**

Impedance, transformed to feed point	49.2Ω- 3.11jΩ
Return Loss	- 29.8dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	46.6Ω- 2.33jΩ
Return Loss	- 27.4dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.508 ns
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After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.
No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

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DASY5 Validation Report for Head TSL

Date: 06.16.2018

Test Laboratory: CTTT, Beijing, China

DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN: 4d154

Communication System: UID 0, CW; Frequency: 835 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 835 \text{ MHz}$; $\sigma = 0.891 \text{ S/m}$; $\epsilon_r = 40.97$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Right Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 - SN7307; ConvF(10.01, 10.01, 10.01); Calibrated: 2/19/2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2018-02-02
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

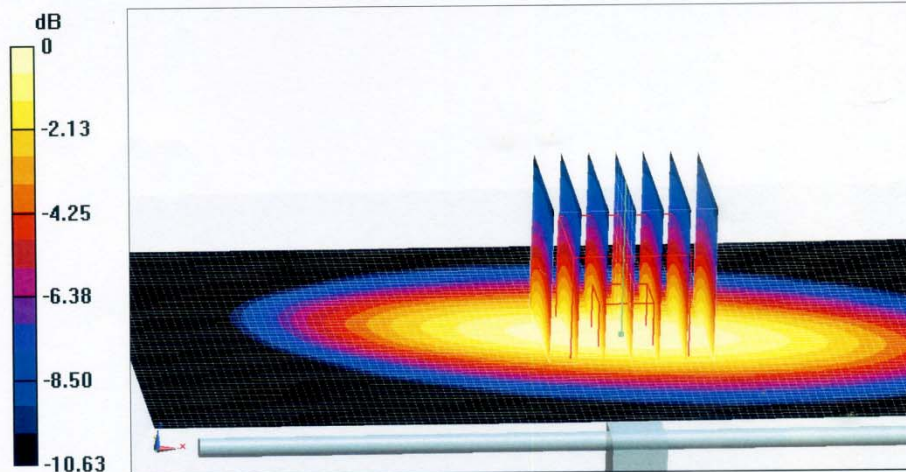
Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 58.14V/m; Power Drift = 0.02 dB

Peak SAR (extrapolated) = 3.41 W/kg

SAR(1 g) = 2.3 W/kg; SAR(10 g) = 1.5 W/kg

Maximum value of SAR (measured) = 2.91 W/kg

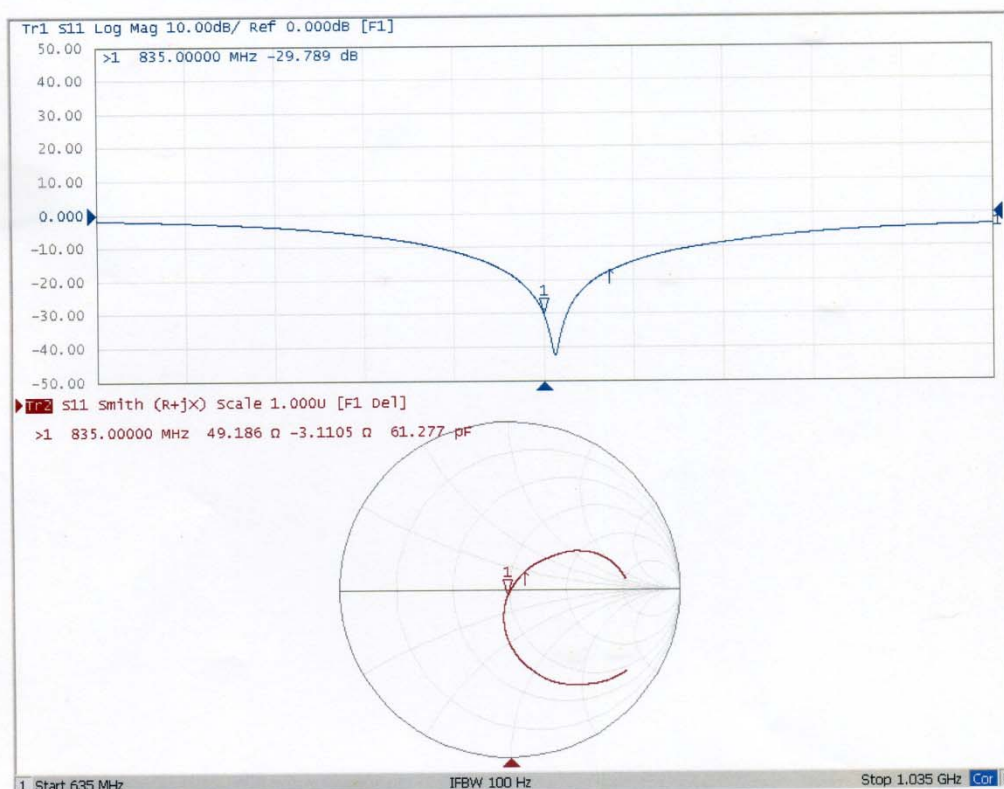




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Impedance Measurement Plot for Head TSL





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DASY5 Validation Report for Body TSL

Date: 06.16.2018

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 835 MHz; Type: D835V2; Serial: D835V2 - SN: 4d154

Communication System: UID 0, CW; Frequency: 835 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 835 \text{ MHz}$; $\sigma = 0.991 \text{ S/m}$; $\epsilon_r = 55.41$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Center Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 - SN7307; ConvF(9.83,9.83, 9.83); Calibrated: 2/19/2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2018-02-02
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

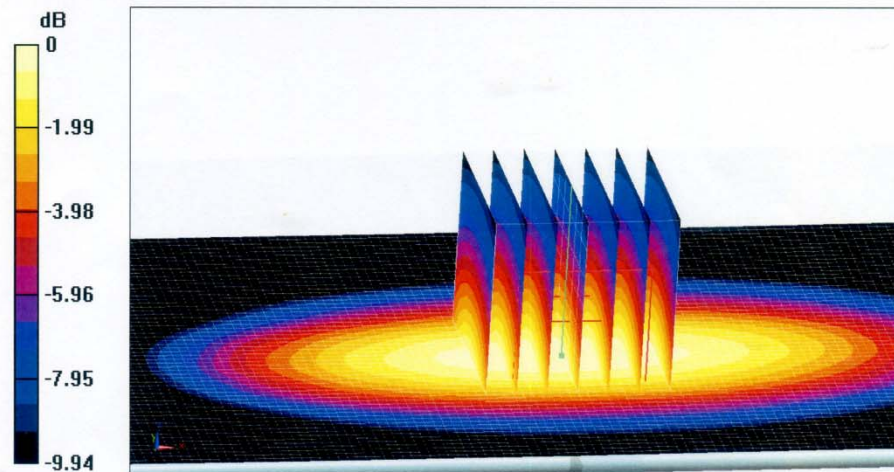
Dipole Calibration/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 54.01 V/m; Power Drift = 0.01 dB

Peak SAR (extrapolated) = 3.53 W/kg

SAR(1 g) = 2.43 W/kg; SAR(10 g) = 1.61 W/kg

Maximum value of SAR (measured) = 3.04 W/kg



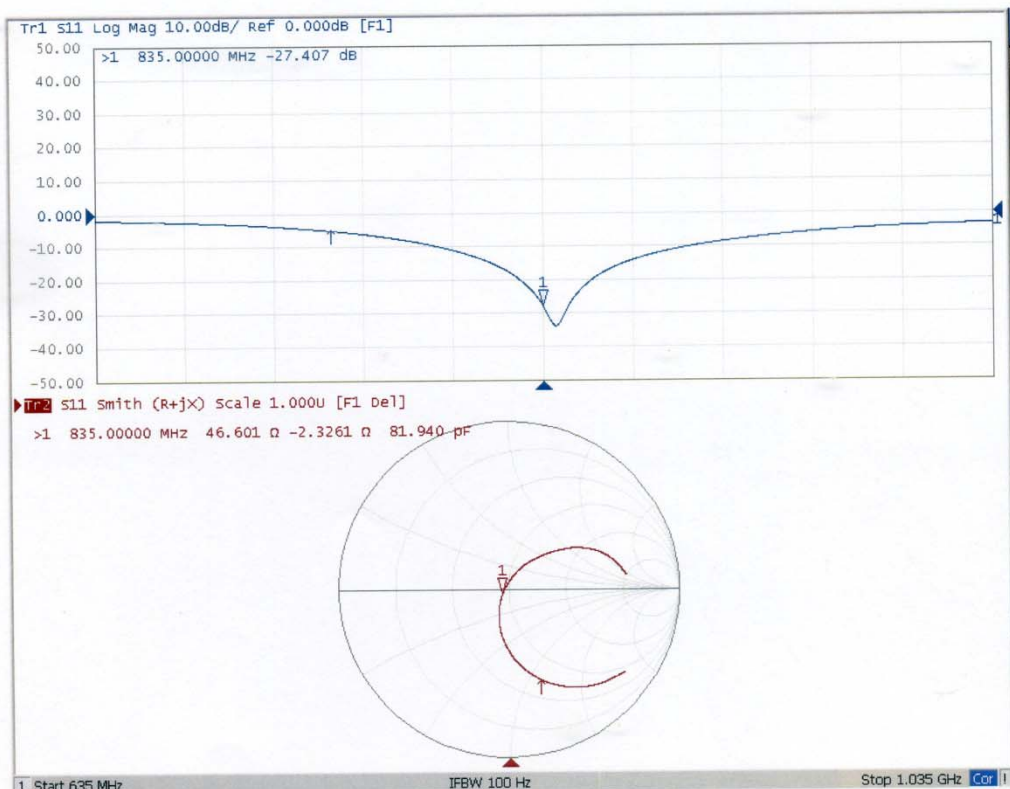
0 dB = 3.04 W/kg = 4.83 dBW/kg



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Impedance Measurement Plot for Body TSL





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DASY5 Validation Report for Body TSL

Date: 06.15.2016

Test Laboratory: CTTL, Beijing, China

DUT: Dipole 1900 MHz; Type: D1900V2; Serial: D1900V2 - SN: 5d175

Communication System: UID 0, CW; Frequency: 1900 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 1900$ MHz; $\sigma = 1.537$ S/m; $\epsilon_r = 53.34$; $\rho = 1000$ kg/m³

Phantom section: Center Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY5 Configuration:

- Probe: EX3DV4 - SN7307; ConvF(7.67, 7.67, 7.67); Calibrated: 2/19/2016;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn771; Calibrated: 2/2/2016
- Phantom: Triple Flat Phantom 5.1C; Type: QD 000 P51 CA; Serial: 1161/1
- Measurement SW: DASY52, Version 52.8 (8); SEMCAD X Version 14.6.10 (7372)

System Performance Check/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid:

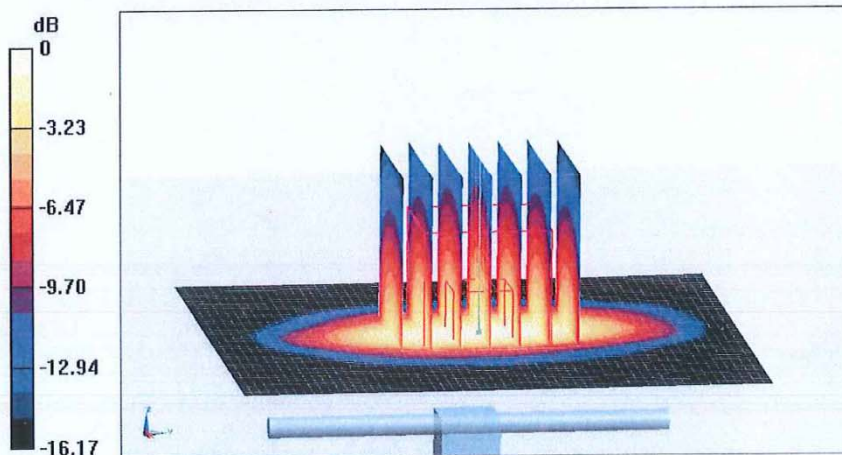
$dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 96.11 V/m; Power Drift = -0.03 dB

Peak SAR (extrapolated) = 17.8 W/kg

SAR(1 g) = 10.1 W/kg; SAR(10 g) = 5.39 W/kg

Maximum value of SAR (measured) = 14.3 W/kg



0 dB = 14.3 W/kg = 11.55 dBW/kg

Certificate No: Z16-97090

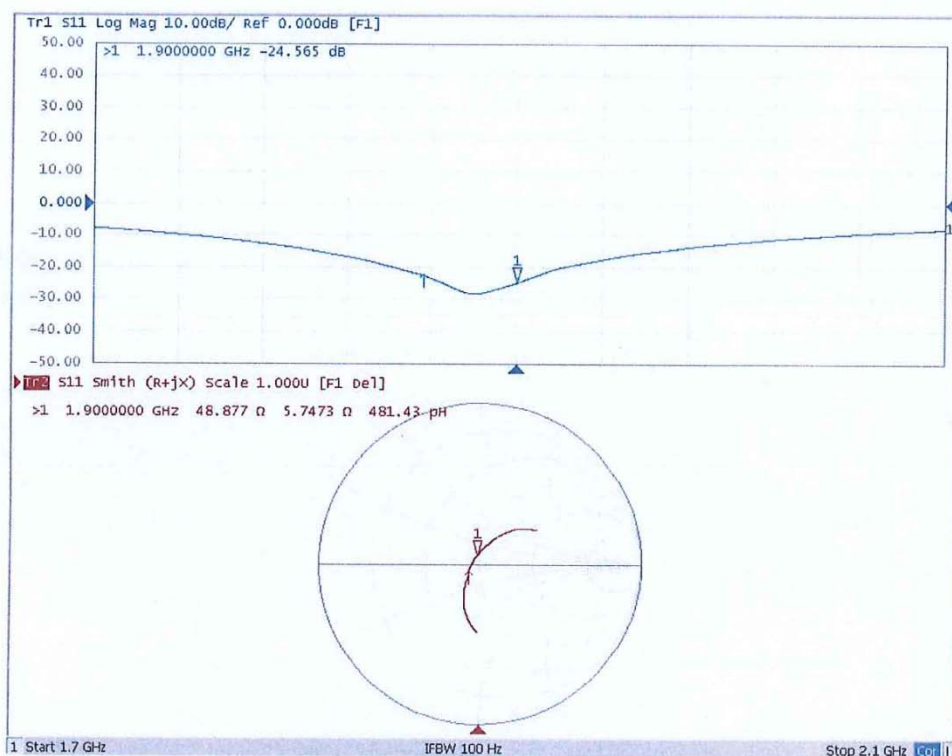
Page 7 of 8



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Impedance Measurement Plot for Body TSL



*****END OF REPORT*****